

Distinguished Lecturer 2024-25 Season



Recommended Practice for Safe Well Positioning, Separation, and Surveying



Jonathan Lightfoot Oxy

Learn More



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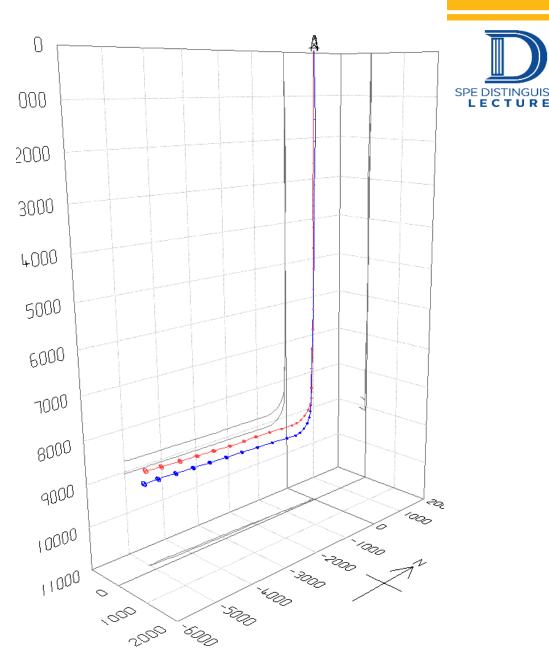
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Presentation Outline

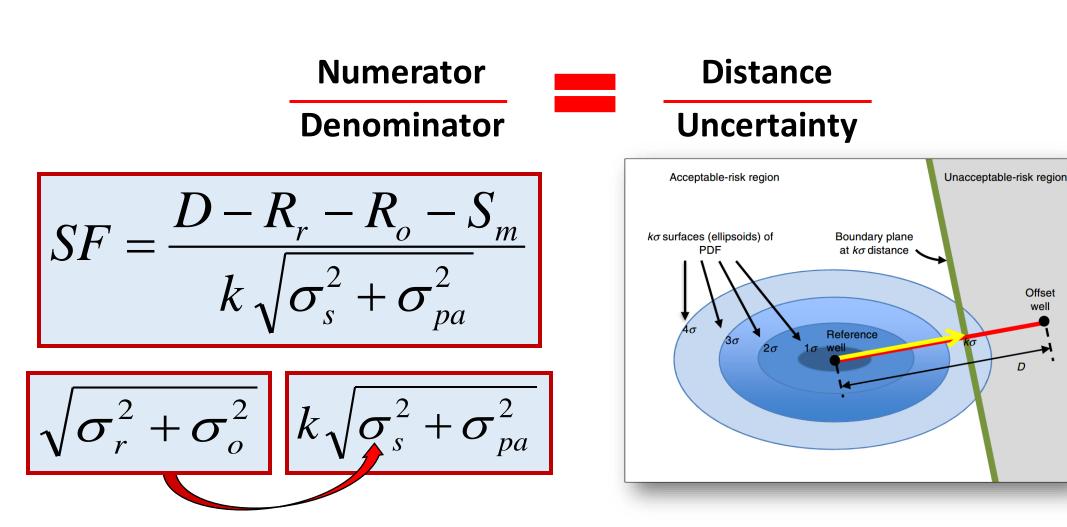
- Safe Separation
- Applications
- Industry Collaboration
- Management Principles
- Position Uncertainty Models (PUMs)
- Offset Well Environment
- Case Studies
 - Offset Operator Close Approach
 - Lateral Undulations
 - Key Performance Indicators
 - Steerable Motor Curve
 - Lateral Tortuosity
- Key Takeaways



WPTS Separation Rule Illustration (SPE-187073-PA)



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Safe Separation The Wellbore Positioning Technical Section (WPTS) Rule Separation Factor = Ratio of Separation Distance and Uncertainty



Applications



Serves as the primary technical reference for proven engineering practice in the broad wellbore construction application of:

- Oil and Gas
- Geothermal
- Carbon Sequestration
- Coalbed Methane (CBM)
- Horizontal Directional Drilling (HDD), trenchless boring
- Mineral Ventilation and Extraction
- Scientific Coring
- All other subsurface borehole construction applications

Industry Collaboration

Industry Steering Committee on Wellbore Survey Accuracy



- Produces, maintains, and publishes standards for the industry
- Promotes a collaborative understanding of issues associated with wellbore surveying
- Formed in 1999, ISCWSA has been around for 29 Years [SPE 67616-PA]
- 57 General Meetings

SPE Wellbore Positioning Technical Section (WPTS)

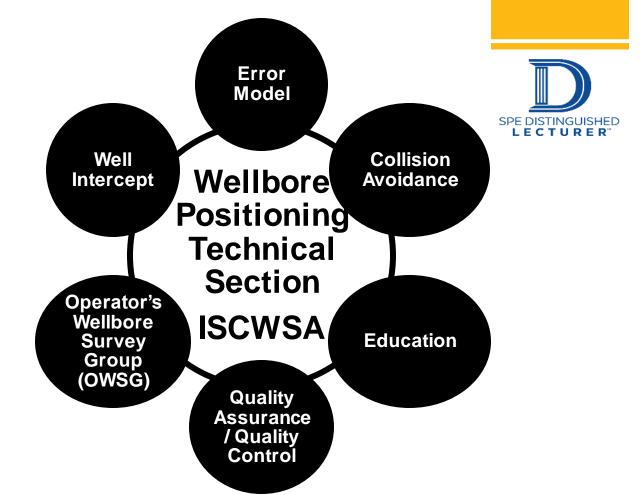




Industry Collaboration

WPTS has Six (6) Primary Sub-Committees

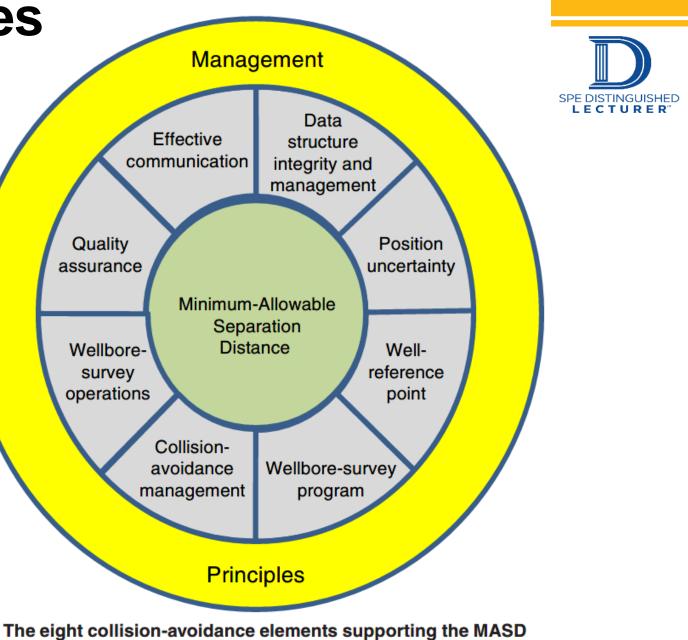
- 1. Collision Avoidance
- 2. Error Model Maintenance
- 3. Well Intercept
- 4. Operator's Wellbore Survey Group
- 5. Quality Assurance / Quality Control
- 6. Education





Management Principles

- Minimum Allowable Separation Distance (MASD)
- Maintain a Safe Separation Distance Between Wells Being Drilled and Subsurface Hazards
- 8 Core MASD Elements



MASD Management Principles (SPE-187073-PA)

Allowable Deviation from Plan for SF=1

Any given SF value represents a specific probability of the reference well crossing the offset well. The distance D at which a particular SF value occurs is situation specific. For any point on a reference well, the critical value SF = 1 defines a minimum allowable separation distance (MASD) from the specified offset well along D:



$$SF = \frac{D - R_r - R_o - S_m}{k\sqrt{\sigma_s^2 + \sigma_{pa}^2}} \qquad SF = \frac{D - R_r - R_o - 0.3}{3.5\sqrt{\sigma_s^2 + 0.25}}$$

$$D_{MASD} = k\sqrt{\sigma_s^2 + \sigma_{pa}^2} + R_r + R_o + S_m$$

Allowable Deviation from Plan for SF=1



$$D_{MASD} = k \sqrt{\sigma_s^2 + \sigma_{pa}^2 + R_r + R_o} + S_m$$

If the distance D falls below D_{MASD} , then SF < 1. The difference between the planned distance D_{plan} and the D_{MASD} is the allowable deviation from the plan D_{ADP} :

$$D_{ADP} = D_{plan} - D_{MASD}$$

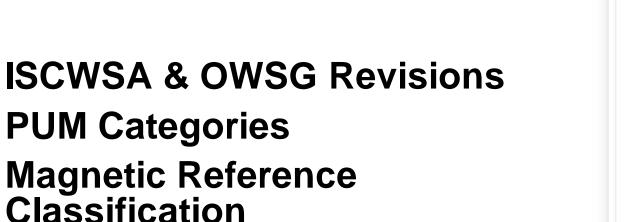
SPE-187073-MS

Well Collision Avoidance - Separation Rule

S.J.Sawaryn, Consultant, H. Wilson, Baker Hughes a GE Company, J. Bang, Gyrodata Inc., E. Nyrnes, Statoil ASA, A. Sentance, Dynamic Graphics Inc., B. Poedjono and R. Lowdon, Schlumberger, I. Mitchell and J. Codling, Halliburton, P.J. Clark, Chevron Energy Technology, W.T. Allen, BP

MASD Management Principles (SPE-187073-PA)

Position Uncertainty Models (PUM)



Generic Models (Set A & B) PUM Example – MWD + SRGM MWD Corrections Definition of the ISCWSA Error Model

ICCIIICO

Revision 5.13 January 2023

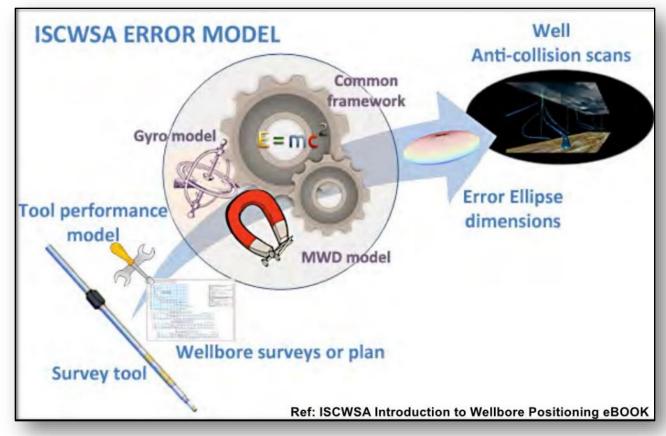


PUM Sets – Established by OWSG

- PUM, often referred to as Error Models or Instrument Performance Models, Revision 5.13 (Current)
- Set A: Standard
- Set B: Extended
- Set C: Vendor-supplied
- Set D: Gyro software validation
- Set E: Prototypes in development

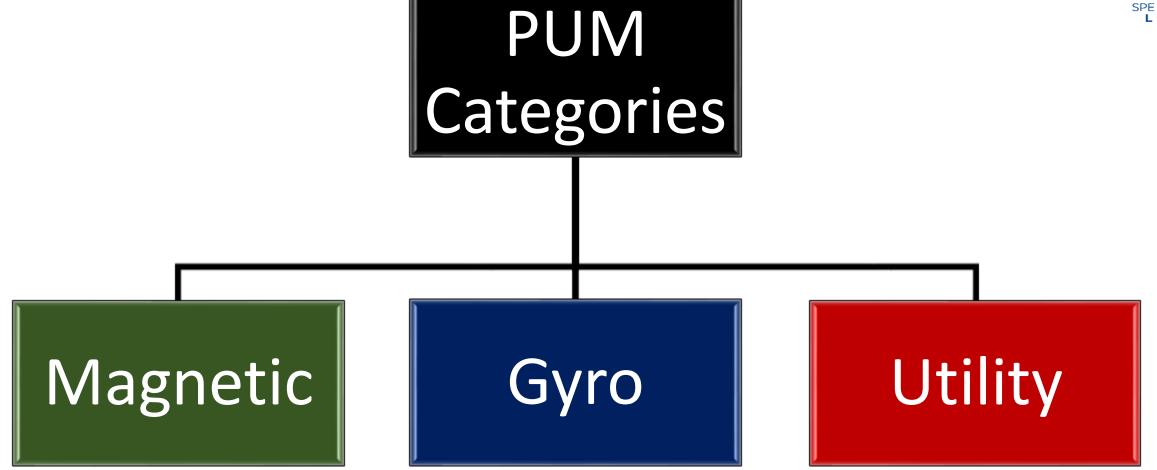
Grindrod, S. J., Clark, P. J., Lightfoot, J. D., Bergstrom, N.. , and L. S. Grant. "**OWSG Standard Survey Tool Error Model Set for Improved Quality and Implementation in Directional Survey Management**." Paper presented at the IADC/SPE Drilling Conference and Exhibition, Fort Worth, Texas, USA, March 2016. doi: <u>https://doi.org/10.2118/178843-MS</u>

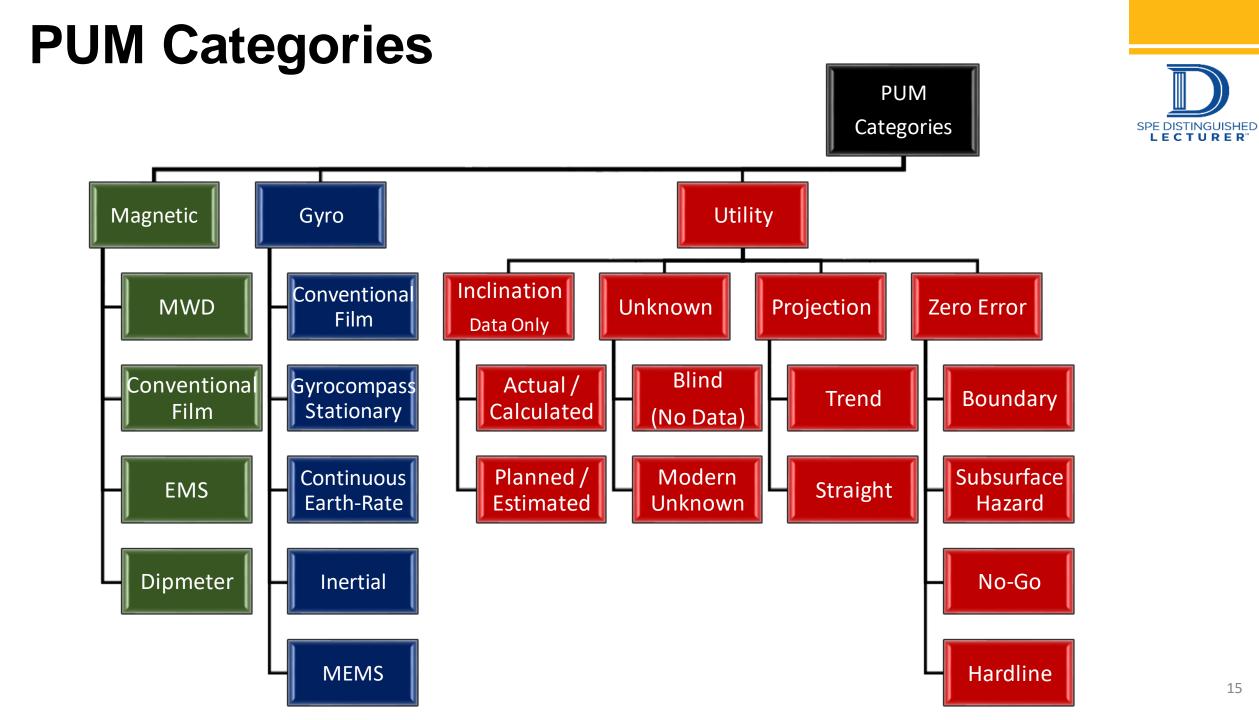




PUM Primary Categories







Position Uncertainty Models (PUM)

| Revision | Revision Date Description | | SPE DISTINGU L E C T U R | | | | | | |
|-----------------------|--|--|--|--|--|--|--|--|--|
| Rev 0 | Dec 2000 | As per SPE 67616 together with various typographical corrections [1] | | | | | | | |
| Rev 1 | March 2005 | Changed to the gyro style misalignment with 4 terms and calculation options [2] | | | | | | | |
| Rev 2 | Feb 2007 | Changes to the parameter values for the depth scale and stretch terms [2] | | | | | | | |
| Rev 3 | Rev 3 Oct 2009 Replacement of all toolface dependent terms | | | | | | | | |
| Rev 4 & OWSG Rev 2 | Mar 2019 | Introduction of AMIL term and changes to misalignment magnitudes. Random magnetic reference values introduced to the main MWD model. OWSG includes Conventional, Gyro and Utility PUMs. Included Low Resolution and High Resolution Magnetic Reference Models for MWD and EMS. [3] | Definition of the ISCWSA Error Model | | | | | | |
| Rev 5 | Oct 2020 | Introduction of the XCL term, changes to misalignments and sag, breakout of magnetic reference terms and clarification of the surface tie-on. [4] | Revision 5.13 January 2023 | | | | | | |
| Rev 5.13 | Rev 5.13 Jan 2023 Minor updates to Rev 5 [4] – Latest Revision | | | | | | | | |
| | | 3-MS | Definition of 1004/3 Entry Model Rev.1.13 | | | | | | |

4. https://www.iscwsa.net/media/files/files/64bd61c2/definition-of-iscwsa-error-model-v5-13.pdf



Magnetic Reference PUM Classification

| Category Abbreviati on | | Example Geomagnetic Models | Wavelen 40,000 km | | Update Frequency |
|---|------|--|------------------------------|------------|---------------------|
| Low Resolution | LRGM | GRF, WMM, CGRF | ≤ 400 | ≤ 4000 km | |
| Standard Resolution | SRGM | MVSD, Pre-BGGM2019 | ≤ 300 | ≤ 300 km | |
| High Resolution | HRGM | HDGM, MVHD, BGGM2019+, HDGM-RT | ≤ 55 km | | Annual |
| In-Field Referencing | IFR1 | IFR, IFR1, Ground shot plus secular variation correction | ≤ 2 km | | Annual |
| In-Field Referencing with Realtime Disturbance Field Correction | IFR2 | IFR2, IIFR | ≤ 2 km p realtime samp | (≤ 1 min) | Annual |
| | | | | Multiplier | Category |
| | | | | 1.21 | LRGM |
| | | | | 1.00 | SRGM |
| | | | | 0.82 | HRGM |



PUM Toolcodes Rev 5-1

A default set of conservative PUM tool-codes for use when tool specific models are not available.

- ISCWSA Generic Toolcodes SetA Rev5-1 (updated Sept 23, 2022)
- ISCWSA Generic Toolcodes SetB Rev5-1 (updated Sept 23, 2022)
- Header / Reference Info
- Weighting Functions
- Technical Reference / Source
- Code & Term Description
- Type, Magnitude & Units
- Correlation Coefficients & Comments
- Formulas (Inclination & Azimuth)

| Ŧ | OWSG Prefix 💌 | Short | Name | | Long Name | | ज | | | | |
|----|------------------|-------|------------------|---|-----------------------|---|---|----------|--|--|--|
| 1 | A001Mc | MWD |)+SRGM | | OWSG MWD+SRGM | D+SRGM | | | | | |
| з | A002Mc | MWD | +SRGM+SAG | | OWSG MWD + SRGM + Sa | OWSG MWD + SRGM + Sag Correction | | | | | |
| 5 | A003Mc | MWD |)+SRGM+AX | | OWSG MWD + SRGM + A | xia | al Correction | | | | |
| 7 | A004Mc | MWD | +SRGM+AX+SAG | | OWSG MWD + SRGM + A | xia | al Correction + Sag Correction | | | | |
| 9 | A005Mc | MWD |)+IFR1 | | OWSG MWD + IFR1 | | | | | | |
| 11 | A006Mc | MWD |)+IFR1+AX | | OWSG MWD + IFR1 + Axi | al | Corr | | | | |
| 13 | A007Mc | MWD | +IFR1+AX+SAG | _ | OWSG MWD + IFR1 + Axi | OWSG MWD + IFR1 + Axial Corr + Sag Correction | | | | | |
| 15 | A008Mc | - | OWSG Prefix | Ŧ | Short Name | <u> </u> | Long Name | . | | | |
| | A009Mc | 1 | B001Mc | | MWD+HRGM | | OWSG MWD + HRGM | | | | |
| | A010Mc | 3 | B002Mc | | MWD+HRGM+AX | | OWSG MWD + HRGM + Axial Correction | | | | |
| | A011Mc | 5 | B003Mc | | MWD+HRGM+AX+SAG | | OWSG MWD + HRGM + Axial Correction + Sag Correction | | | | |
| | A012Mc | 7 | B004Mc | | MWD+HRGM+SAG | | | | | | |
| | A013Mc A014Mc | 9 | B005Mc | | MWD+HRGM+SAG+MS | | OWSG MWD + HRGM + Sag + Multi-Station Correction | | | | |
| | A015Mc | - | B006Mc | | MWD+LRGM | | OWSG MWD + LRGM | | | | |
| | A016Mc | | B007Mc | | MWD+LRGM+AX | | OWSG MWD + LRGM + Axial Correction | | | | |
| | A017Mc | | | | | | | | | | |
| 35 | A018Mb | | B008Mc | | MWD+LRGM+AX+SAG | A | OWSG MWD + LRGM + Axial Correction + Sag Correction | | | | |
| 37 | A019Gb | 17 | B009Mc | | MWD+LRGM+SAG | | QW <u>IG1</u> WD+LRG Line ag Correction | | | | |
| 39 | A020Gb | 19 | B010Mc | | EMS+IFR1+AX+SAG | | WSG EMS HFR1 + toral Corr + Sag Correction | | | | |
| 41 | A021Gc | 21 | B011Mc | | EMS+IFR1+SAG | | OWSG EMS + IFR1 + Sag Correction | | | | |
| 43 | A022Gb | 23 | B012Mc | | EMS+IFR1+SHE+MS | | OWSG EMS + IFR1 + Seg + Multi-Station Correction | | | | |
| 45 | A023Gb | 25 | B013Mc | | EMS+HRGM | Γ | | | | | |
| 47 | A024Mb | 27 | B014Mc | | EMS+HRGM+AX | 4 | OWSG EMS + HRGM + Axial Correction | | | | |
| 49 | A025Mb | 29 | B015Mc | | EMS+HRGM+AX+SAG | | OWSG EMS + HRGM + Axial Correction + Sag Correction | | | | |
| 51 | A026Ua | 31 | B016Mc | | EMS+HRGM+SAG | | OWSG EMS + HRGM + Sag Correction | | | | |
| 53 | А027Ub | | B017Mc | | EMS+LRGM | | OWSG EMS + LRGM | | | | |
| | A028Ub | | B017MC B018Md | | EMS+LRGM+AX | | OWSG EMS + LRGM + Axial Correction | | | | |
| | A029Ub | | | | | | | | | | |
| 59 | A030Ua | | B019Md | | EMS+LRGM+AX+SAG | | OWSG EMS + LRGM + Axial Correction + Sag Correction | | | | |
| | | 39 | B020Mc | | EMS+LRGM+SAG | | OWSG EMS + LRGM + Sag Correction | | | | |
| | | 41 | B021Ga | | FINDS | | OWSG BHI Ferranti FINDS | | | | |
| n | 1 | 42 | B022Ua | | BLIND+TREND | | OWSG BLIND+TREND | | | | |

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Example: A001Mc MWD+SRGM



https://www.iscwsa.net/error-model-documentation/ ISCWSA_Generic_Toolcodes_SetA_Rev5-1 (updated 23/9/22) Excel Workbook Tab: MWD+SRGM

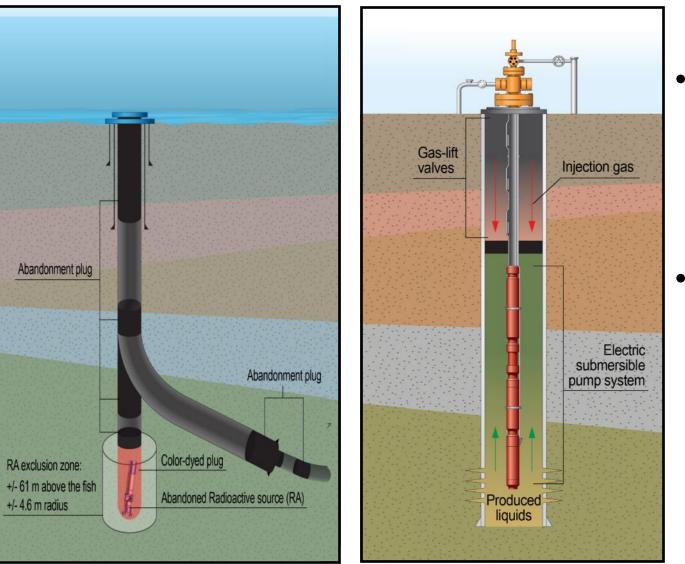
| 01Me | MVD+SRGM | | | | | | | | | | | | |
|------------------------|--|------------|---|--------|--------------------------------|--------------|---------------|---------|---------|--------------------------------|----------|--|--|
| 011-10 | | | | | | | | | | | | | |
| 'SG Prefix: | A001Mc | No Code | Term Description | ¥t.Fn. | ¥t.Fn. Source | Туре | Magnitude Un | nits Pr | rop. P1 | P2P3 ¥t.Fn. Comment | Depth Fo | rm Inclination Formula | Azimuth Formula |
| ort Name: | MWD-SRGM | 1 DRFR | Depth: Depth Reference - Random | DREF | SPE 67616 | Depth | 0.35 r | m f | R 0 | 0 0 | 1 | 0 | 0 |
| Name: | OVSG MVD+SRGM | 2 DSFS | Depth: Depth Scale Factor - Systematic | DSF | SPE 67616 | Depth | 0.00056 | - 3 | S 1 | 0 0 | MD | 0 | 0 |
| ision No: | 5.1 | 3 DSTG | Depth: Depth Stretch - Global | DST | SPE 67616 | Depth | 0.00000025 1/ | lm (| G 1 | 1 1 | MD*TVD | 0 | 0 |
| ision Date: | 8-Oct-20 | 4 ABXY-TI | MWD TF Ind: X and Y Accelerometer Bias | ABXY-T | SPE 63275 + Andy Broo | Sensor | 0.004 m | ls2 | S 1 | 0 0 | 0 | -Cos(Inc) / Gfield | (Tan(Dip) * Cos(Inc) * Sin(AzM)) / Gfield |
| | Reading changed to match ISCWSA Modelin (Rev.5), XCLA & XCLH terms added, XYM3 | | | | | | | | | | | | |
| | relief buildings. XVAH anglaced by IE, SAG anglaced by GAGE, DECG replaced by IF (2014) (SAG anglaced by IF (2014) (SAG anglaced by IF (2014)) | | | | | | | | | | | | |
| sion Comment: | | 5 ABXY-TI | 2 MWD TF Ind: X and Y Accelerometer Bias | ABXY-T | SPE 63275 + Andy Broo | Sensor | 0.004 m | is2 | S 1 | 0 0 Singularity when vertical | 0 | 0 | ((Tan((pi / 2) - Inc)) - Tan(Dip) * Cos(AzM)) / Gfield |
| ce: | Owact - Shipperfold and wood to | 6 ABZ | MWD: Z-Accelerometer Bias | | SPE 67616 Table 1 | Sensor | 0.004 m | | S 1 | | 0 | -Sin(Inc) / Gfield | Tan(Dip) * Sin(Inc) * Sin(AzM) / Grield |
| | MWD using 1-Year Standard Resolution Geomagnetic Mode (e.g. BGGM up to 2018, MVSD) | | | _ | | | | | | | | | |
| cation: | with no additional corrections | | S MWD TF Ind: X ar | 19 | SPE 63275 | Sensor | 0.0005 | - 3 | S 1 | 0 0 | | Sin(Inc) * Cos(Inc) / Sqr(2 | (-Tan(Dip) * Sin(Inc) * Cos(Inc) * Sin(AzM)) / Sqr(2) |
| Type: | Mag | | 2 MWD TF Ind: X an poel ete e Fac | | SPE 63275 SPE 63275 + Ano, | Sen | 905 | | | | | | (Dip os(Inc) * Sin(AzM)) / 2 |
| | eterence | | MWD TF Ind: X ar | ` 🔺 | SPE 63275 + Ano, | en | 5 | | 1 | 0 | | | (1 p) nc, s(AzM) - Cos(Inc)) / 2 |
| ked: | | 10 ASZ | MWD: Z-Accelero | ۶Z | SPE 67616 | en | 45 | | | | | | (In h(AzM) |
| oved: | | 11 MBXY-TI | 1 MWD TF Ind: X and T Magnetometer Blas | MBX1- | SPE 63275 + Anagono | 5 Sen | 70 7 | 11 · | 5 1 | | | | -cos(Inc) - sin(AzIvi) r (BFier - Cos(Dip)) |
| 8 | Based on ISCWSA MWD Rev 3 (Tool Face Independent - Sliding) | 12 MBXY-TI | 2 MWD TF Ind: X and Y Magnetometer Bias | MBXY-1 | SPE 63275 + Andy Broo | Sen a | 70 n | nT : | S 1 | 0 0 | 0 | 0 | Cos(AzM) / (BField * Cos(Lp)) |
| ion History: | Rev 0.105-Jun-2013 Draft Release for Comment. | 13 MBZ | MWD: Z-Magnetometer Bias | MBZ | SPE 67616 Table 1 | Sensor | 70 n | nT 🔅 | S 1 | 0 0 | 0 | 0 | -Sin(Inc) * Sin(AzM) / (BField * Cos(Dip)) |
| | | 14 M TI | TF Use and Y Magnetome sale Factor | MSXY-T | SPE 632 ndy Broo | o Sensor | 0.0016 | - 3 | s | | 0 | 0 | Sin(Inc) * Sin(AzM) * (Tan(Dip) * Cos(Inc) |
| | ev 8 ,201 C A 1777 et AL c an t A | 15 M3 | F and Whitneetometry Coale Easter | HIGXY- | 632 <mark>75 A</mark> nde Deeg | nos en cor | 00010 | - 1 | s | | | | Cip(4-14)* (Tap(Di-24 Cip(Inc) * Cos(Inc) |
| i/i ac iy: | | 16 MS | A A A A A A A A A A A A A A A A A A A | - Y | - 05 2' nd | | - | - 1 | s | | | | 22 Ct 240-cos(AzM) - Cos (AzM) |
| ation Range Min: | 0 deg | 17 MS2 | WD ne er soare f a | | 676 de | S r | 9.0 | - 1 | s | | 0 | | in(Costerney (Dip) * Cos |
| ation Range Max: | 180 deg | 18 DEC- | /IWD Nation ed E | | 6 | A | | leg 1 | V . | | | | Sin(Inc) * Sin(AzV)* (Tan(Dip) * Cos(Inc) Cos(Inc) * Sin(AzV)* (Tan(Dip) * Cos(Inc) Cos(Inc) * Cos(Inc) * Cos(Inc) Cos(Inc) * Cos(Inc) * Cos(Inc) in(Inc) Cos(Inc) * Cos(Inc) in(Inc) Cos(Inc) * Cos(Inc) Cos(Inc) * Cos(Inc) * Cos(Inc) Cos(Inc) * Cos(Inc) * Co |
| East/West Exclusion: | 0 deg | 19 DEC-OS | MWD: Declination Crustal Omission Error | AZ | SPE 67616 | AziRef | d | leg (| G 1 | 1 1 | 0 | 0 | 1 |
| je Comment: | None | 20 DEC-OH | MWD: Declination Crustal Omission HD Models | AZ | SPE 67616 | AziRef | 0.21 d | leg (| G 1 | 1 1 | 0 | 0 | 1 |
| Parameters | | 21 DEC-01 | MWD: Declination Crustal Omission IFR Models | 07 | SPE 67616 | ≜ziRef | 0.05 d | leg (| G 1 | 1 1 | 0 | 0 | 1 |
| lignment Alt: | 3 | 22 DECR | MWD: Declination - Random | | PE 67616 | ziRef | 0.1 d | leg f | R 0 | 0 | | 0 | 1 |
| ignment Min Course Len | gtt 10 m | 23 DBH-U | MWD: BH Dependent Declination Uncorrelated Errors | овн 🦳 | SPE | ziF | 50 | т | 1 | | | ons | 17 (BField * Cos(Dip)) |
| Fortuosity: | 1 deg / 100 ft | 24 DBH-OS | MWD: BH Dependent Declination Crustal Omission Standard | рвн | SPE | zil | 3359 | т | 1 | 1 | | | 17 (BField * Cos(Dip)) |
| | | 25 DBH-OH | MWD: BH Dependent Declination Crustal Omission HD Models | · · | AR C | ziFi | 40 | • | 1 | | | | 17 (BField * Cos(Dip)) |
| | | 26 DBH-01 | MWD: BH Dependent Declination Crustal Omission IFR Models | DBH | SPE 67616 | AziRef | 356 deg | g.nT (| G 1 | 1 1 | 0 | 0 | 17 (BField * Cos(Dip)) |
| | | 27 DBHR | MWD: BH-Dependent Declination - Random | DBH | SPE 67616 | AziRef | 3000 deg | g.nT f | R 0 | 0 0 | 0 | 0 | 1/(BField*Cos(Dip)) |
| | | 28 AMIL | MWD: Axial Interference - SinI.SinA | AMIL | Halliburton | Mgntos | 220 n | nT : | S 1 | 0 0 | 0 | 0 | Sin(Inc) * Sin(AzM) / (BField * Cos(Dip)) |
| | | 29 SAGE | MWD: Sag | SAGE | ISCVSA | Align | 0.2 d | leg : | S 1 | 0 0 | 0 | (Sin(Inc))^0.25 | 0 |
| | | 30 XYM1 | Misalignment: XY Misalignment 1 | XYM1 | SPE 90408 Table 9 - Alt | t. Align | 0.1 d | leg : | S 1 | 0 0 | 0 | Abs(Sin(Inc)) | 0 |
| | | 31 XYM2 | Misalignment: XY Misalignment 2 | XYM2 | SPE 90408 Table 9 - Alt | t. Align | 0.1 d | leg : | S 1 | 0 0 | 0 | 0 | 4 |
| | | 32 XYM3E | Misalignment: XY Misalignment 3 | XYM3E | ISCWSA | Align | 0.3 d | - | R 0 | 0 0 Singularity when vertical | 0 | Cos(Inc) * Cos(AzT) * Max(1, sqrt(10/(ME | D-MDPre (Cos(Inc) * Sin(AzT) / Sin(Inc)) * Max(1, sqrt(10/(MD-MD |
| | | 33 XYM4E | Misalignment: XY Misalignment 4 | XYM4E | ISCVSA | Align | 0.3 d | leg l | | 0 0 Singularity when vertical | 0 | | MDPrev (Cos(Inc) * Cos(AzT) / Sin(Inc)) * Max(1, sqrt(10/(MD-M |
| | | 34 XCLA | Depth: Long Course Length XCL - Azimuth | XCLA | SPE 187249 Jerry Codli | | 0.167 | - | | 0 0 Tangential Calculation. Si | ngi O | 0 | Max(Sin(Abs(AzT-AzPrev)), XCLTortuosity* (MD-MD |
| | | | Depth: Long Course Length XCL - Inclination | | SPE 187249 Jerru Codli | | | | | 0 0 Tangential Calculation. Fo | - | Max(Abs(Inc-IncPrev), XCLTortuositu" (I | |

MWD PUM Survey Corrections

- Axial (AX)
- Sag
- Multi-Station Analysis (MSA or MS)
- Axial + Sag
- Multi-Station + Sag
- Depth Corrections
- Advanced MWD Corrections
 - Ground Shot (GS) IFR
 - Advanced Multi-Station (AMSA)
 - All BHA's for a Wellbore
 - All BHA's for all wellbores on a well (Includes Sidetracks / By-Pass Wellbores)
 - All BHA's for all wellbores on a Site/Location/Pad



Offset Well Environment



MASD Management Principles (SPE-187073-PA)

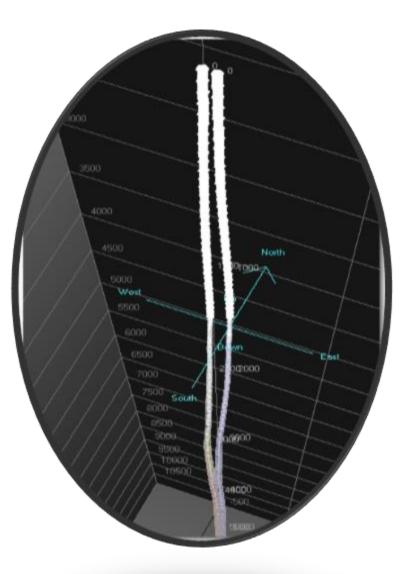


Offset Well Environment

- Status
- Completion Type
- Wellbore Fluids
- Lifting Mechanism
- Artificial Lift
 - Rod Pump
 - Progressive Cavity
 - Hydraulic Pump
 - Gas Lift (GL)
 - Electric Submersible Pump (ESP)
 - Hybrid Lift System
 - GL & ESP
 - ESP & Natural Flow

Case Study

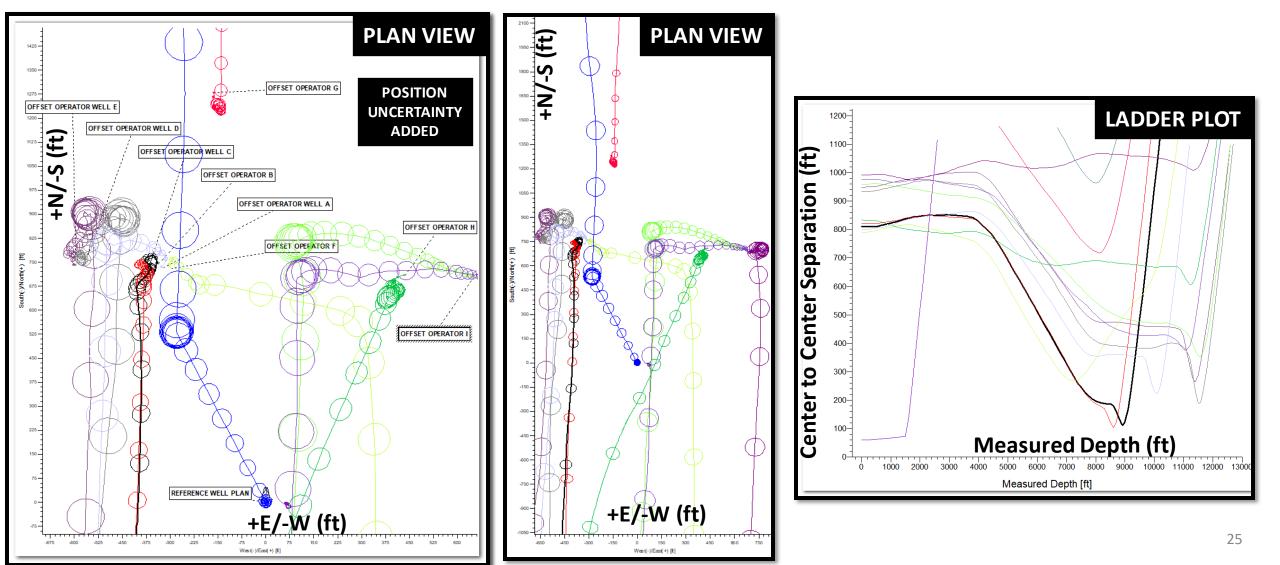
Offset Operator Close Approach



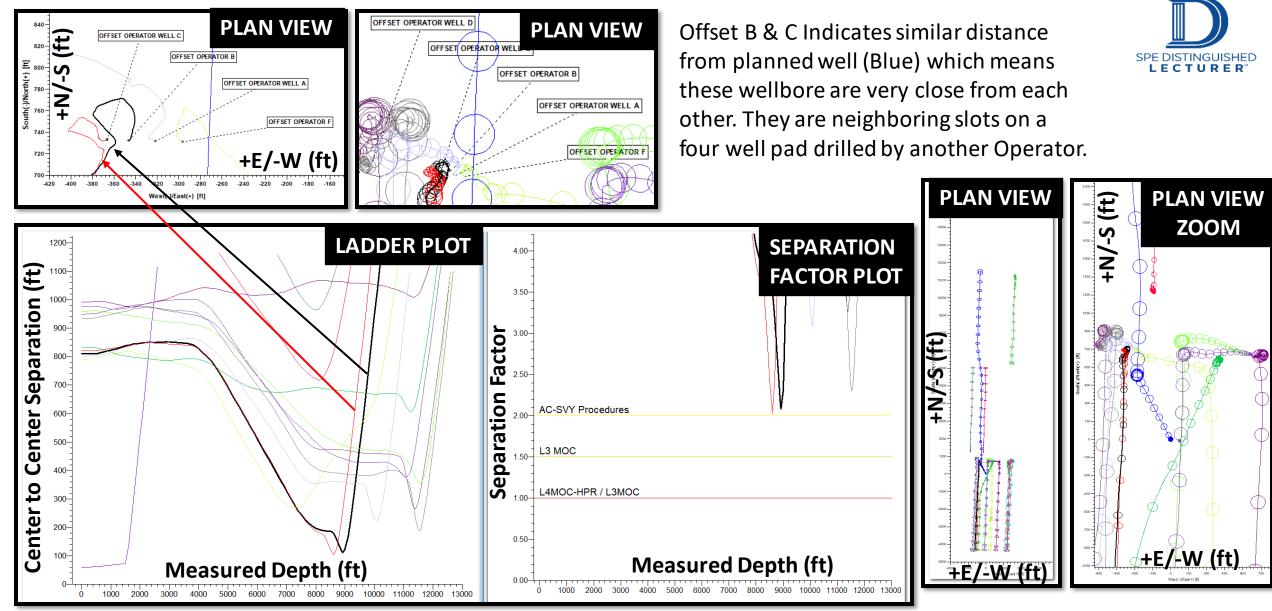


Safe Separation Plots – Ladder & Separation Factor

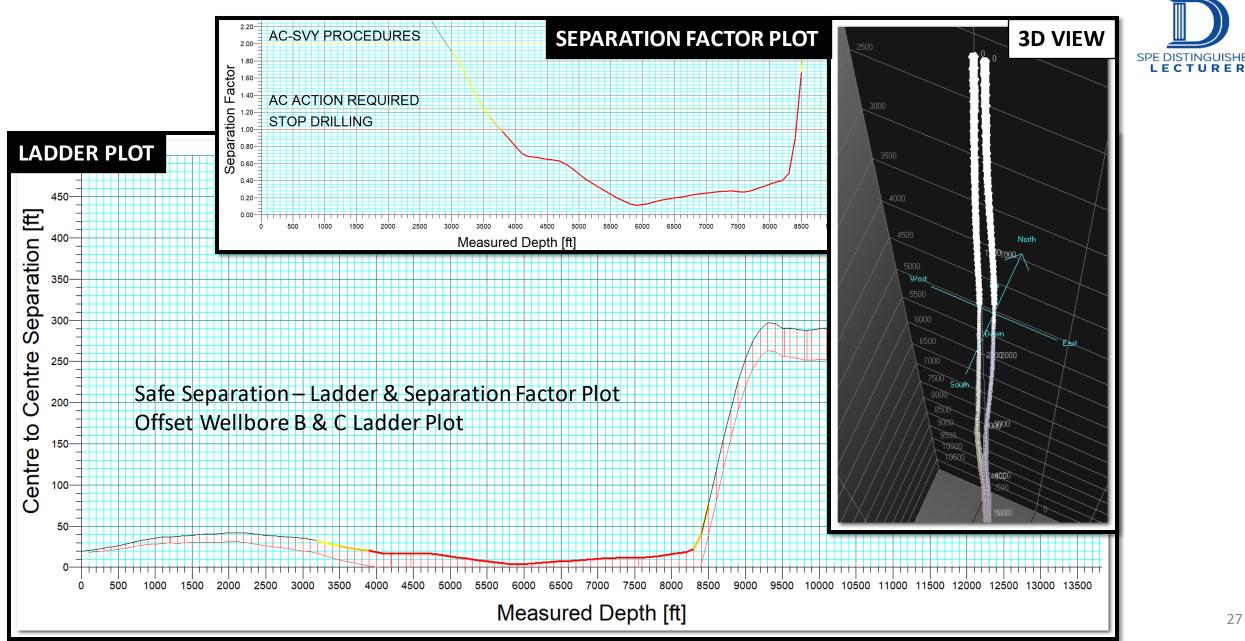




Safe Separation Plots – Ladder & Separation Factor



Safe Separation Plots – Ladder & Separation Factor



Case Study

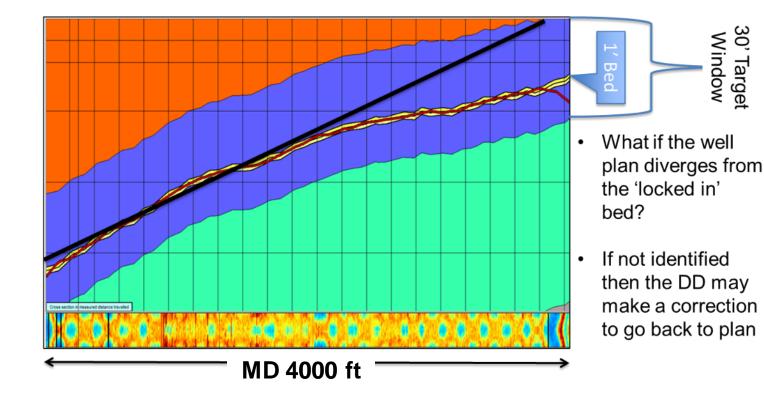
Lateral Undulations Key Performance Indicators Steerable Motor Curve Lateral Tortuosity



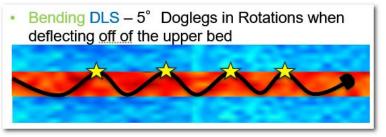


Lateral Undulation Period - TVD Accuracy

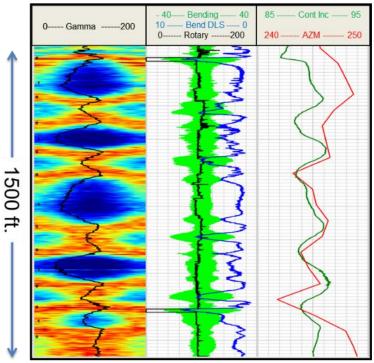




Viens, Christopher, Clark, Tyler, Lightfoot, Jonathan, and Carlos Mercado. "**Real-Time Downhole Data Resolves Lithology Related Drilling Behavior."** Paper presented at the IADC/SPE Drilling Conference and Exhibition, Fort Worth, Texas, USA, March 2018. doi: <u>https://doi.org/10.2118/189697-MS</u>

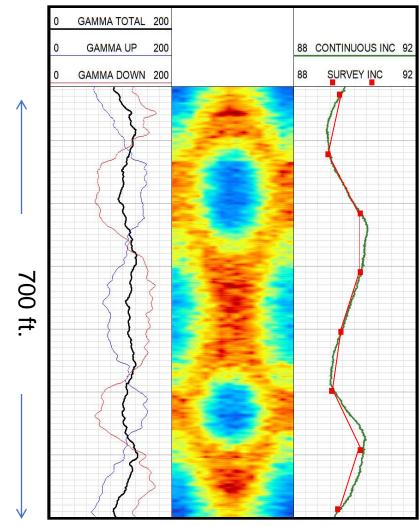


Pad 3 Well A



Lateral Undulation Period - TVD Accuracy

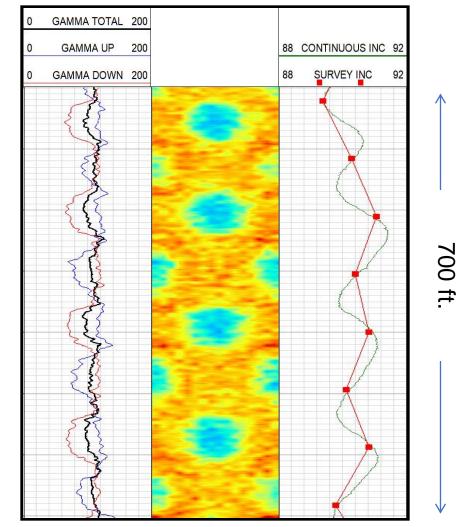
Pad 2 Well A



Left: 90' surveys adequate to due large period of oscillation

Right: 90' surveys inadequate to short oscillation period

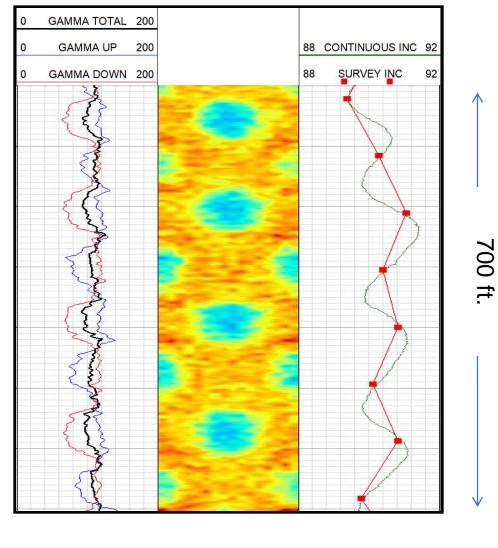


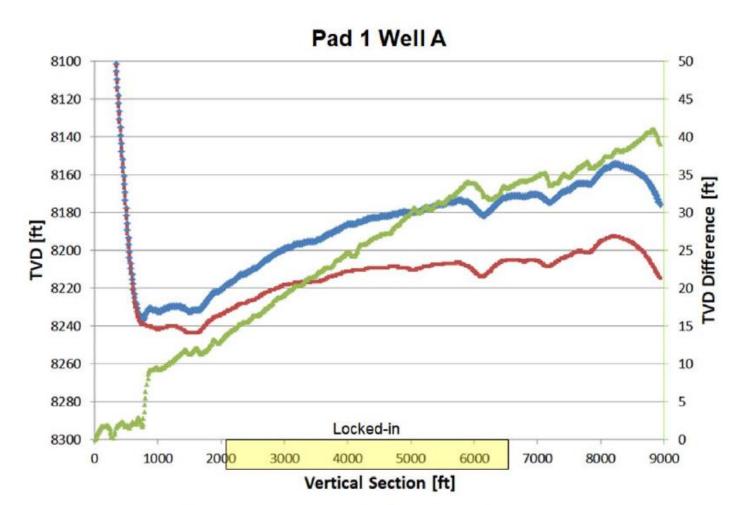




Lateral Undulation Period - TVD Accuracy

Pad 1 Well A





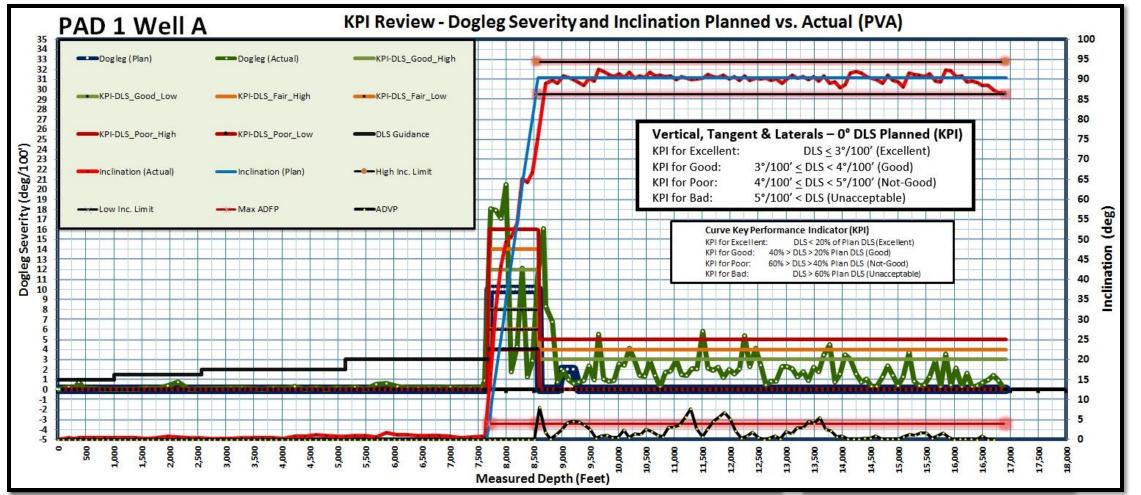
IADC/SPE-189697-MS

31

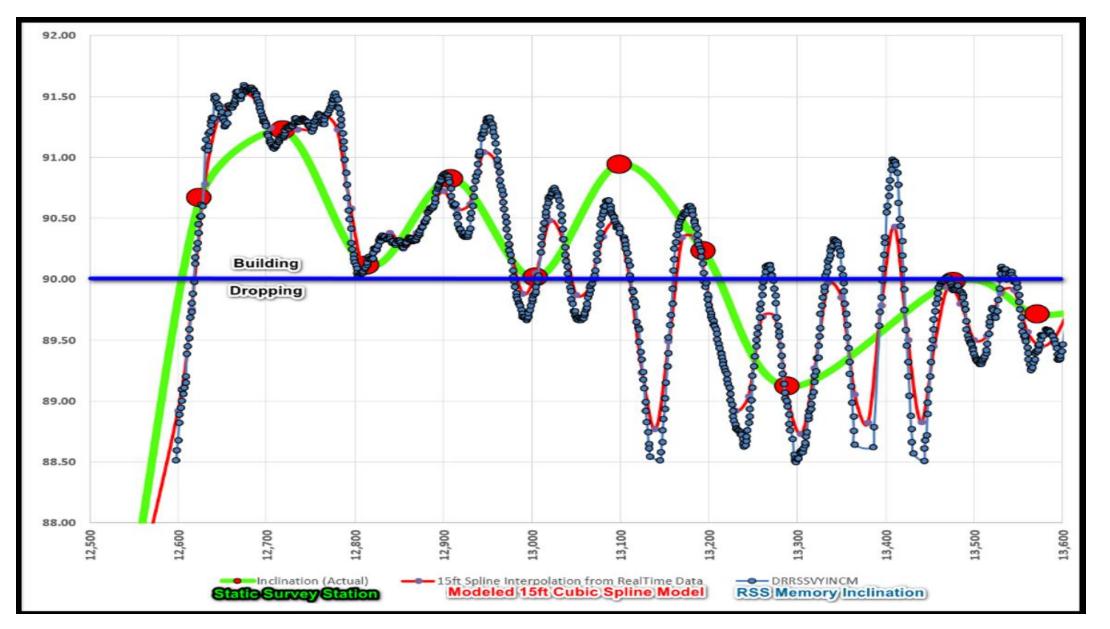
SPE DISTINGUISHED LECTURER^{**}

Directional Drilling Key Performance Indicators





Lateral Undulation Period – RSS Example



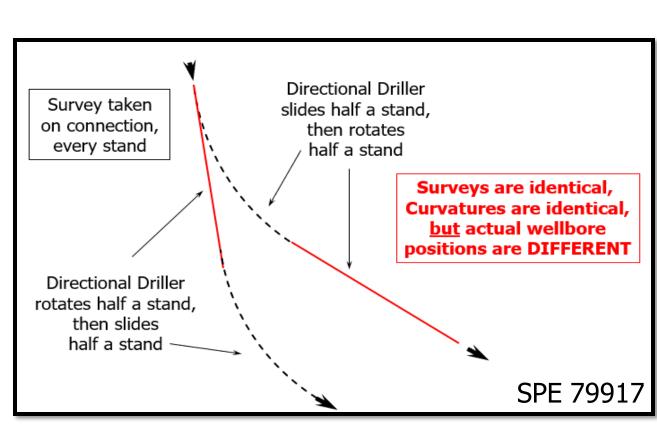


Slide / Rotate Effect – Curve TVD Accuracy

Starting Survey = 10,000 ft MD Inclination 30° & Azimuth 45°

- Case A: Slide 30 ft then Rotate 70 ft @ 10°/100'
- Case B: Rotate 70 ft then Slide 30 ft @ 10°/100' Final Inclination 40° & Final Azimuth 45°
- Case A: Survey at 10,030' & at 10,100'
- DLS 16.7°/100 ft & TVD 9,082.6 ft
- Case B: Survey at 10,070' & at 10,100'
- DLS 16.67°/100 ft & TVD 9,085.9 ft
- Case C: Survey only at 10,100'
- DLS 5°/100 ft & TVD 9,084 ft

Case A vs. Case B have a TVD difference 3.29 ft over only 100 ft of MD (1-Stand)





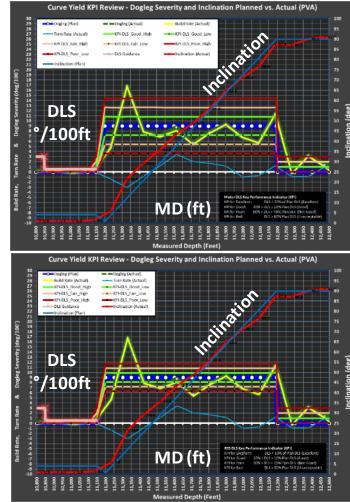
Directional Drilling Key Performance Indicators



Directional Drilling Dogleg Severity Control Key Performance Indicators

| Directional Tools & Hole Section Type | Excellent | Good | Not-Good | Unacceptable RCRA Required | |
|---|---------------------------------|----------------------------------|----------------------------------|---------------------------------|--|
| Vertical Intervals | DLS <u><</u> 2 | 2 < DLS <u><</u> 3 | 3 < DLS ≤ 4 | 4 < DLS | |
| Tangent Intervals | DLS≤2 | 2 < DLS <u><</u> 3 | 3 < DLS ≤ 4 | 4 < DLS | |
| Lateral Intervals | DL\$ <u><</u> 2 | 2 < DLS <u><</u> 3 | 2 < DLS ≤ 3 3 < DLS ≤ 4 | | |
| Directional Motor Steering Interval | DLS < +/- 20% of Planned DLS | Between 20-40% of Planned DLS | Between 40-60% of Planned DLS | DLS > +/- 60% of Planned DLS | |
| Directional RSS Steering Interval | DLS < +/- 10% of Planned DLS | Between 10-20% of Planned DLS | Between 20-30% of Planned DLS | DLS < +/- 30% of Planned DLS | |

Offset Operator Motor Curve



Motor Curve KPI Chart 20-40-60%

RSS Curve KPI Chart 10-20-30%

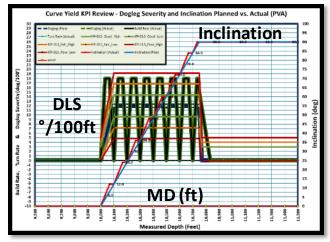
Slide / Rotate Effect – Curve TVD Accuracy



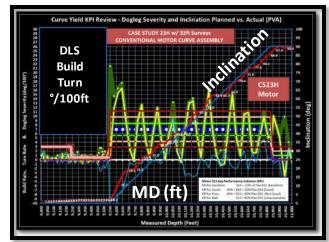
Case A: Slide 33 ft, Rotate 33 ft and Slide 33 ft from 0° to 90° Inc.

| MD | Inclination (Actual) | Azimuth (Actual) | Course Length | TVD | Vertical Section | +N / - S | +E / -W | Colosure Distance | @ AZM | Dogleg (Actual) | Build Rate (Actual) | Turn Rate (Actual) |
|-----------|-------------------------|---------------------|---------------|----------|---------------------|----------|---------|----------------------|---------------|-----------------|------------------------|-----------------------|
| 0.00 | 0.00 | 45.00 | *** | | 0.00 | 0.00 | 0.00 | 0.00 | | 0.00 | *** | *** |
| 10,000.00 | 0.00 | 45.00 | | 10000.00 | 0.00 | 0.00 | 0.00 | 0.00 | 45.00 | 0.00 | 0.00 | 0.00 |
| 10,033.33 | 6.00 | 45.00 | 33.33 | 10033.27 | 1.26 | 1.23 | 1.23 | 1.75 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,066.67 | 12.00 | 45.00 | 33.33 | 10066.18 | 5.03 | 4.92 | 4.92 | 6.96 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,100.00 | 12.00 | 45.00 | 33.33 | 10098.78 | 10.05 | 9.82 | 9.82 | 13.89 | 45.00 | 0.00 | 0.00 | 0.00 |
| 10,133.33 | 18.00 | 45.00 | 33.33 | 10130.97 | 16.29 | 15.92 | 15.92 | 22.51 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,166.67 | 24.00 | 45.00 | 33.33 | 10162.07 | 24.92 | 24.36 | 24.36 | 34.45 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,200.00 | 24.00 | 45.00 | 33.33 | 10192.52 | 34.73 | 33.95 | 33.95 | 48.01 | 45.00 | 0.00 | 0.00 | 0.00 |
| 10,233.32 | 30.00 | 45.00 | 33.33 | 2222.21 | 45.67 | 64 | 44.64 | € .13 | \$5.00 | 18.00 | 18.00 | 0.00 |
| 10,26/ 66 | 36.00 | 45.00 | 33.33 | 19250-15 | 58,80 | 57.47 | 57-47 | ٤.28 | 45.00 | 18-00 | 19-00 | 0.00 |
| 10,30 .00 | 36. | 45.00 | 33.33 | 27 12 | 7. 98 | | 71. | 1 0.87 | \$5.00 | J.00 | 0.0 | 0.00 |
| 10,33 83 | 42.00 | 45.00 | 33.33 |)30: 01 | 8 15 | £ 1.1 | 86.:) | 1 1.84 | 4 .0(| .8.00 | 18.00 | 0.00 |
| 10,366.6 | 48. | 45.00 | 33.33 | J32C.57 | 105 | 1_2.81 | 1021 | 40 الما 1 | 1 5.00 | 1 18.00 | | 0.00 |
| 10,400.00 | 48.00 | 45.00 | 33.33 | 10348.87 | 123.11 | 120.33 | 120.33 | 170.17 | 45.00 | 0.00 | 0.00 | 0.00 |
| 10,433.33 | 54.00 | 45.00 | 33.33 | 10369.84 | 141.84 | 138.64 | 138.64 | 196.06 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,466.66 | 60.00 | 45.00 | 33.33 | 10387.99 | 162.06 | 158.40 | 158.40 | 224.01 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,500.00 | 60.00 | 45.00 | 33.33 | 10404.66 | 182.94 | 178.81 | 178.81 | 252.87 | 45.00 | 0.00 | 0.00 | 0.00 |
| 10,533.33 | 66.00 | 45.00 | 33.33 | 10419.78 | 204.42 | 199.80 | 199.80 | 282.56 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,566.66 | 72.00 | 45.00 | 33.33 | 10431.72 | 226.92 | 221.79 | 221.79 | 313.67 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,599.99 | 72.00 | 45.00 | 33.33 | 10442.02 | 249.86 | 244.21 | 244.21 | 345.37 | 45.00 | 0.00 | 0.00 | 0.00 |
| 10,633.33 | 78.00 | 45.00 | 33.33 | 10450.64 | 273.14 | 266.97 | 266.97 | 377.55 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,666.66 | 84.00 | 45.00 | 33.33 | 10455.86 | 296.94 | 290.24 | 290.24 | 410.46 | 45.00 | 18.00 | 18.00 | 0.00 |
| 10,699.99 | 84.00 | 45.00 | 33.33 | 10459.34 | 320.93 | 313.68 | 313.68 | 443.61 | 45.00 | 0.00 | 0.00 | 0.00 |
| 10,733.33 | 90.00 | 45.00 | 33.33 | 10461.08 | 345.00 | 337.20 | 337.20 | 476.88 | 45.00 | 18.00 | 18.00 | 0.00 |

SIMULATED EXAMPLE



ACTUAL EXAMPLE

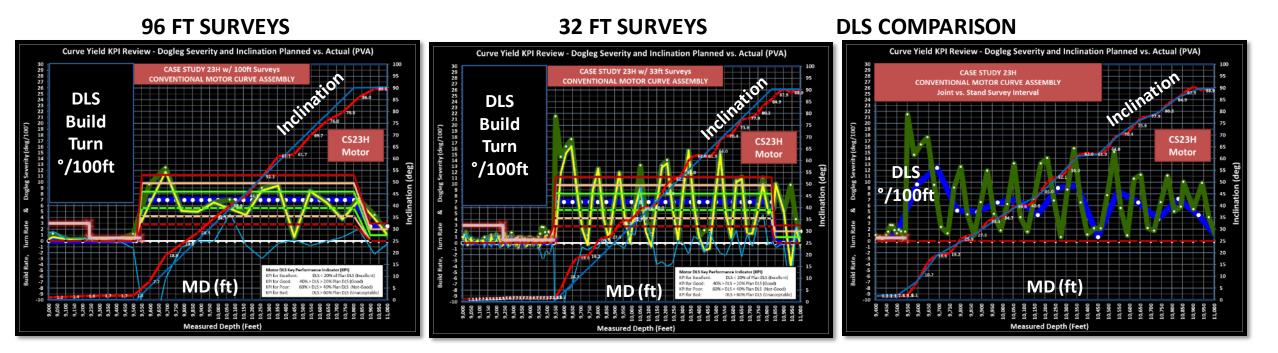


Case B: Survey Every 100 ft from 0° to 90° Inc. (16 ft TVD Delta)

| | MD (Plan) | Inclination (Plan) | Azimuth (Plan) | Course Length | TVD | Vertical Section | +N / - S | +E / -W | Closure | @ AZM | Dogleg (Plan) | Build Rate | Turn Rate |
|---|-----------|-----------------------|-------------------|------------------|----------|---------------------|----------|---------|---------|-------|------------------|---------------|--------------|
| | 0.00 | 0.00 | 0.00 | | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 | | 0.00 | *** | **** |
| T | 10,000.00 | 0.00 | 45.00 | 10000.00 | 10_0.00 | | 0 | 0.00 | .00 | | 0.00 | 0.00 | 0.45 |
| 1 | 10,100.0 | 00 | 5.00 | 100.00 | 10 79.57 | 7.55 | 7 38 | | : .43 | 45.0 | | | 2.00 |
| 1 | 10,200. | 00 | .00 | 100.00 | 10 94.5 | 9. 6 | 2: 19 | 29.1 | 428 | 5.0 | 2.00 | | 0.00 |
| 1 | 10,300.0 | 3# 10 | 45.00 | .00.00 | 10 30.6 | 65. 114.29 | 6 48 | 64.4 | 919 | | 2.00 | 2.00 | 0.00 |
| 1 | 10,400.00 | 48.00 | 45.00 | 100.00 | 10554.85 | 114.29 | 111.71 | 111.74 | 157.98 | 45.00 | 12.00 | 12.00 | 0.00 |
| 1 | 10,500.00 | 60.00 | 45.00 | 100.00 | 10413.50 | 172.71 | 168.81 | 168.81 | 238.73 | 45.00 | 12.00 | 12.00 | 0.00 |
| 1 | 10,600.00 | 72.00 | 45.00 | 100.00 | 10454.10 | 238.68 | 233.29 | 233.29 | 329.92 | 45.00 | 12.00 | 12.00 | 0.00 |
| | 10,700.00 | 84.00 | 45.00 | 100.00 | 10474.85 | 309.32 | 302.33 | 302.33 | 427.56 | 45.00 | 12.00 | 12.00 | 0.00 |
| | 10,750.00 | 90.00 | 45.00 | 50.00 | 10477.46 | 345.42 | 337.62 | 337.62 | 477.46 | 45.00 | 12.00 | 12.00 | 0.00 |

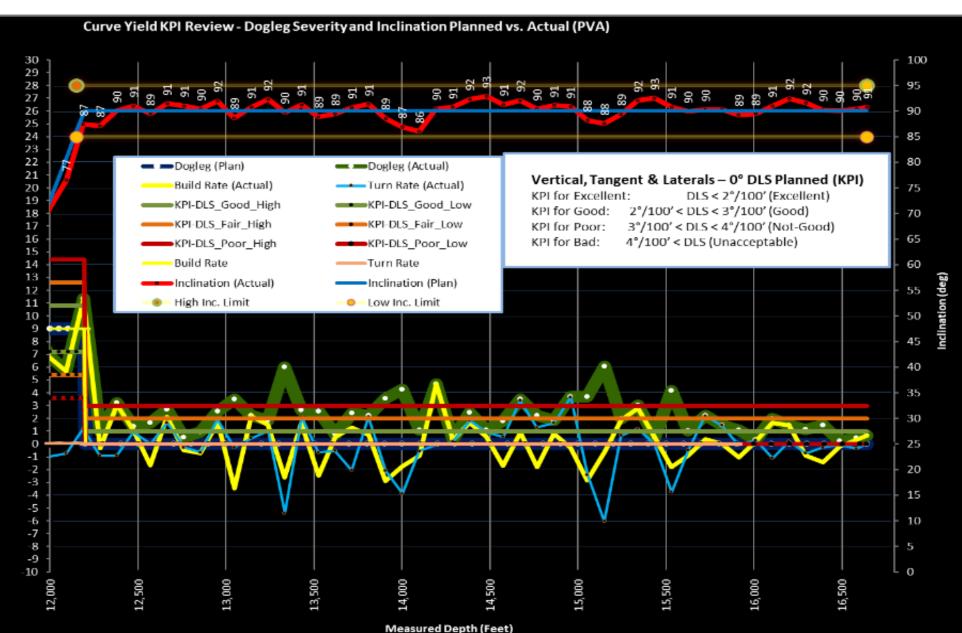
Case Study - Steerable Motor Curve

- Survey Frequency is Important for Medium Radius Curves
- If slide % is less, consider surveying twice a stand or every joint
- When sliding 90 to 100%; survey is less prone to landing TVD error





Lateral Tortuosity KPI – Case Study

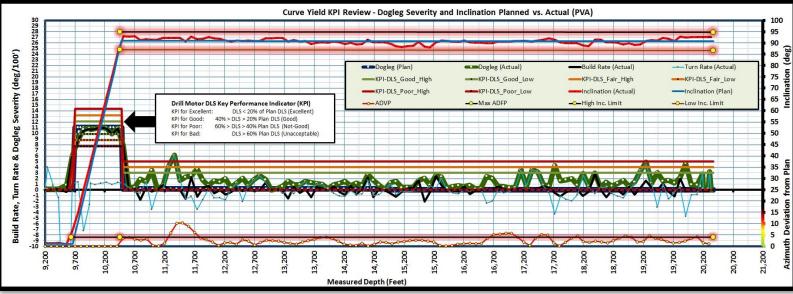




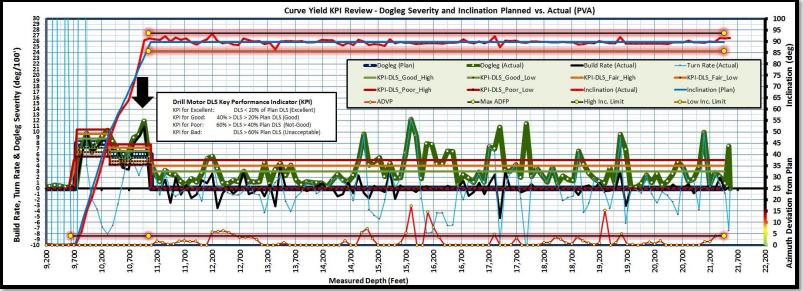
Lateral DLS Build & Turn Rate KPI Chart With Inclination +/- Allowable Deviation from Plan

Surface to TD DLS KPI Chart with Artificial Lift DLS Guidance for Surface & Intermediate

Case Study – RSS Low Tortuosity



Case Study – RSS High Tortuosity





Curve Lateral Tortuosity KPI RSS Examples

Key Takeaways

- As demonstrated in these case studies, Safe Separation collision avoidance methods are designed to safely separate wellbores while also improving wellbore position accuracy.
- The survey interval should be considered during both the drilling planning and execution phases.
- Key performance indicators aid in achieving the objectives and expectations of directional wells.
- Wellbore Surveying and Positioning Practices
 - Provides a primary source of technical information for all subsurface borehole construction applications.
 - Contributes to the modernization of the wellbore construction industry by promoting safe separation procedures.
 - All participants in wellbore construction should support the collaborative effort of a committed group of industry volunteers. The desired outcome is industry-wide adoption.

See the WPTS for more information: https://connect.spe.org/wellborepositioning





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